

# K.S. SCHOOL OF ENGINEERING AND MANAGEMENT, BENGALURU - 560109 DEPARTMENT OF MECHANICAL ENGINEERING

SESSION: 2020-2021 (EVEN SEMESTER)

#### CO-PO MAPPING

				PO MAP	PING					
Cours Type:		emat	ics of Machines	Com	rse Code: 18M	F44				
Type.	Core		No	of Hours	se Code. Tolvi					
Theory (Lecture Class)		Pra	actical/Field Work/Allied			Total tea	Total teaching hours			
	3		0			42				
				Marks						
Inter	nal Assessme	nt	Examination		Total		Credits			
	40 Objectives of		60		100		3			
1. 2.	Familiariz Understan	e wi	th mechanisms and motion ethods of mechanism motor on of planar mechanisms,	tion analy	sis and their o	haracteristics.				
	se Learning to		omes urse, the students will be ab	ole to						
CO1			ement diagrams for follor e drawing for various fol		various type	s of motions	s K3 Applying			
CO2	Understand motion stu	K2 Understanding								
соз	Evaluating the transmission of power by application of various gears and gear trains.						K4 Analyzing			
CO4	Construction Graphical	_	elocity and acceleration o	diagrams	for planar me	K4 Analyzing				
CO5				eration of planar mechanisms by complex algebra thesis of four bar and slider crank kinematic						
			Syllah	ous Conte	nt					
Modu		ams	, types of followers. disp			acceleration	CO1 10 hrs			
curve:	s for unifor dation, Cyc ating follow	m v loida	relocity, Simple Harmon al motion. Cam profile naving knife-edge, roller	nic Motio	on, Uniform cam with rec	Acceleration ciprocating /	PO1-3 PO2-3 PO3-2 PO4 - 2 PO5-1			
			nalysis of are cam with fl session the student will b				PO12 -1 PSO1-3 PSO2-1			

- Understand the concept of cams and analysis of cams
   Construct cam profile for specific follower motion
   Explain the concept symmetric cams

Module 2:	
<b>Introduction:</b> Definitions: Link, kinematic pairs, kinematic chain, mechanism, structure, degrees of freedom, Classification links, Classification of pairs based on type of relative motion, Grubler's criterion, mobility of mechanism, Groshoff's criteria, inversions of Grashoff's chain.	<b>CO2</b> 10 hrs.
Mechanisms: Quick return motion mechanisms-Drag link mechanism, Whitworth	
mechanism and Crank and slotted lever Mechanism. Oldham's coupling, Straight	PO1-3
line motion mechanisms Peaucellier's mechanism and Robert's mechanism.	PO2-3 PO3-2
	PO3-2 PO4-2
Intermittent Motion mechanisms: Geneva wheel mechanism, Ratchet and Pawl	PO5-1
mechanism, toggle mechanism, pantograph, condition for correct steering,	PO6-1
Ackerman steering gear mechanism.	PO12-1
LO: At the end of this session the student will be able to,	PSO1-3
Understand the mechanism analysis	PSO2-1
Explain different mechanisms	
Understand the terminology of mechanisms	
Module 3:  Spur Gears: Gear terminology, law of gearing, path of contact, arc of contact, contact ratio of spur gear. Interference in involute gears, methods of avoiding interference, back lash, condition for minimum number of teeth to avoid interference, expressions for arc of contact and path of contact  Gear Trains: Simple gear trains, compound gear trains. Epicyclic gear trains: Algebraic and tabular methods of finding velocity ratio of epicyclic gear trains, torque calculation in epicyclic gear trains  LO: At the end of this session the student will be able to.  1. Explain concept of interference and minimum number of teeth 2. Understand the motion transmission through gear trains 3. Explain Gear terminology and law of gearing 4. Understand the concept of path of contact, arc of contact	CO3 10 hrs PO1-3 PO2-3 PO3-2 PO4-2 PO5-1 PO6-1 PO12-1 PSO1-3 PSO2-1
4. Olderstand the concept of path of contact, are of contact	1302-1
Module 4:	CO4 10hrs
Velocity and Acceleration Analysis of Mechanisms (Graphical	101118
INTERPRETATION AND ADDITIONAL ADDITIONAL ADDITIONAL ATTAINST BAR MACHINEM CHARLES ATTAINS	
	PO1-3
mechanism. Mechanism illustrating. Coriolis component of acceleration. Angular	PO1-3 PO2-3
mechanism. Mechanism illustrating. Coriolis component of acceleration. Angular velocity and angular acceleration of links, velocity of rubbing.	PO2-3 PO3-2
mechanism. Mechanism illustrating. Coriolis component of acceleration. Angular velocity and angular acceleration of links, velocity of rubbing.  Velocity Analysis by Instantaneous Center Method: Definition, Kennedy's	PO2-3 PO3-2 PO4-2
	PO2-3 PO3-2

<b>Klein's Construction</b> : Analysis of velocity and acceleration of single slider crank mechanism.	PO12-1 PSO1-3 PSO2-1
<ol> <li>LO: At the end of this session the student will be able to.</li> <li>Determine position, displacement, velocity and acceleration of various parts in mechanisms.</li> <li>Apply the knowledge of graphical method &amp; instantaneous centre method to determine velocity and acceleration of links</li> </ol>	
Module 5: Velocity and Acceleration Analysis of Mechanisms (Analytical Method): Velocity and acceleration analysis of four bar mechanism, slider crank	CO5 10hrs
mechanism using complex algebra Method.	PO1-3
Freudenstein's equation for four bar mechanism and slider crank mechanism.	PO2-3
Function Generation for four bar mechanism	
	PO4-1
LO: At the end of this session the student will be able to,	PO5-1
Understand the Concept of analytical method to determine velocity and	PO6-1
acceleration of links.	PO12-1
Understand mechanism synthesis.	PSO1-3
Apply the knowledge of mechanism synthesis to evaluate function generation	PSO2-1
Text Books	
1 CAT DOOKS	
1. Theory of Machines, Rattan S.S. Tata McGraw Hill Publishing Company Ltd., New Delhi, 3rd Edition, 2009.	

## Reference Books (specify minimum two foreign authors text books)

- Michael M Stanisic, Mechanisms and Machines-Kinematics, Dynamics and Synthesis, Cengage Learning, 2016.
- Sadhu Singh, Theory of Machines, Pearson Education (Singapore)Pvt. Ltd, Indian Branch New Delhi, 2nd Edi. 2006.
- 3. Theory of Machines, Thomas Beavan

#### Useful Websites

- http://www.sciencedirect.com/
- https://nptel.ac.in/courses/112104114/
- https://www.youtube.com/playlist?list=PL46AAEDA6ABAFCA78

#### **Useful Journals**

- www.journals.elsevier.com/mechanism-and-machine-theory
- www.sciencedirect.com/journal/journal-of-mechanisms

Klein's Construction: Analysis of velocity and acceleration of single slider crank mechanism.	PO12-1
	PSO1-3 PSO2-1
O: At the end of this session the student will be able to.	1302-1
Determine position, displacement, velocity and acceleration of various parts in mechanisms.	
2. Apply the knowledge of graphical method & instantaneous centre method	
to determine velocity and acceleration of links	
Module 5:	
Velocity and Acceleration Analysis of Mechanisms (Analytical	CO5
Method): Velocity and acceleration analysis of four bar mechanism, slider crank	10hrs
nechanism using complex algebra Method	DO1 2
reudenstein's equation for four bar mechanism and slider crank mechanism.	PO1-3 PO2-3
Function Generation for four bar mechanism	PO3-2
	PO4-1
LO: At the end of this session the student will be able to.	PO5-1
Understand the Company of analytical method to determine velocity and	PO6-1
acceleration of link	PO12-1 PSO1-3
2. Understand mechanism synthesis.	PSO2-1
Apply the knowledge of mechanism services to evaluate function generation  Text Books	
New Delhi, 3rd Edition, 20 2. Mechanism and Machine Theory. A G. Ambekar PHI, 2007	
Reference Books (specify mann to a lign authors text books)	
1. Michael M Stanisic, Mechanisms and Machines-Kinematics, Dynamics and Synthe	sis, Cengag
Learning, 2016.	
2. Sadhu Singh, Theory of achines. The Education (Singapore)Pvt. Ltd, Indian	Branch New
Delhi, 2nd Edi. 2006.	
3. Theory of Machines, Thomas Beauty	
Useful Websites	7 3
http://www.sciencericericeric	
• https://nptel.ac.in/courses/11.2	
<ul> <li>https://www.youtube.com/plantablist=PL46AAEDA6ABAFCA78</li> </ul>	
Www.journals.elsevier.com/ps	
www.sciencedirect.com/journal-of-mechanisms	
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### Teaching and Learning Methods

1. Lecture class: 42 hours

Practical classes: 0 hours

#### Assessment

Type of test/examination: Written examination

Continuous Internal Evaluation(CIE): 40 marks (30 marks -Average of three tests + 10 marks

Assignments)

Semester End Exam(SEE): 100 marks (students have to answer all main questions) which will be reduced

to 60 Marks.

Test duration:

1:30 hours

Examination duration: 3 hours

#### CO to PO Mapping

PO1: Science and engineering Knowledge

PO2: Problem Analysis

PO3: Design & Development

PO4:Investigations of Complex Problems

PO5: Modern Tool Usage

PO6: Engineer & Society

PO7: Environment and Society

PO8: Ethics

PO9: Individual & Team Work

PO10: Communication

PO11: Project Mngmt & Finance

PO12: Life long Learning

PSO1: Ability to apply concept of mechanical engineering to design a system, a component or a process/system to address a real world challenges

PSO2: Ability to develop effective communication, team work, entrepreneurial and computational skills

со	PO	PO1	PO2	PO3	PO 4	PO5	PO6	PO 7	PO8	PO9	PO10	PO1 1	PO12	PS O1	PS O 2
17 ME44	K-level											= "			
CO1	K3	3	3	2	2	1		-	-	-	-	1-0	1	3	
CO2	K2	3	3	2	2	1	-1	-			-	-20	1	3	1
CO3	K4	3	3	2	2	1	1	-	-	-	-	7/	1	3	1
CO4	K4	3	3	2	2	1	1	-	-	-		-	1	3	1
CO5	K4	3	3	2	1	1	1		-	-	•	-	1	3	1

Principal